

\*\*\*\*\*Last Edit 01April09, Art was Kind enough to fill in the Unknown stuff, so now the document is complete!!!\*\*\*\*\*  
(no not an april fools joke).

UPDATE to Mach Specific VB routines:

The currently “Undocumented”, (not on the Wiki), VB routines.

Brain sent the VB header file and I tested the ones I haven’t seen before.

There is also some “Odds and Ends” VB thrown in from various post that are useful as well.

The “Undocumented” VB:

1). System VB:

HelpAbout() //returns Mach VB script version

Random() //generates fractional random number

DoMenu(sub, pos) //sub is menu items across the bar starting at 0 i.e. File = 0, pos is the position of the submenu item under the main menu so: DoMenu(0,0) would activate the Open “Load G-code”, submenu under the “File” main menu.

NotifyPlugins(int#) //a number you want to send from VB to your Plug-in, to do something in your plugin.

```
MachMSG( "Message", "Title", type) //type 1-6  
'int 0=OK button  
'int 1= OK, CANCEL button  
'int 2= Abort, Retry, Ignore buttons  
'int 3= Yes, No, Cancel buttons  
'int 4= Yes, No  
'int 5= Rety, Cancel  
'int 6= Cancel, Try Again, Continue
```

VerifyAxis(Silent) // is Move to zero to rehome the axis and then back to start position, no report of error or lost steps that are detected. The 1 or 0 is report or not, VerifyAxis(0) they all move to home position and then come off of home not error reporting, and (1) will do the same plus report lost step errors.

SingleVerify(axis) //axis 0-5, Will do a VarifyAxis above except will do a Single axis and NOT report lost step errors.

SingleVerifyReport(axis) // axis 0-5, Will do a VarifyAxis above except will do a Single axis and WILL report lost step errors.

QueueDepth() // current amount in the motion queue ( motion commands holding to be done).

IsWiz() //detects if a Wizard is running

StartVideo(); //Starts the Video Window Up.

\*\*\*\*\*VBTest(); //Deprecated NO LONGER USED!!!!\*\*\*\*\*

SetProbeActive(bool) // turns the probe ON or off, 1 for on, 0 for off

SetProbeState(bool) // sets the low-active on or off, 1 for on, 0 for off

CoupleSlave(bool) //sets the slave axis to home exactly with the master axis 1 for on, 0 for off

2). Axis related:

StraightTraverse(double x, y, z, a, b, c) //move to a point shortest path

GetScale(axis) //axis 0-6

SetScale(axis,double Scale) //axis 0-6

SetMachZero(axis) // axis 0-6, this will set this to a Machine ZERO!!

GetABSPosition(axis) //axis 0-6, gets the machine coordinate of that axis

MinX(), MaxX(), MinY(),MaxY() // gets the max/min of a program in X/Y  
JogOn(axis#, dir) //axis# = 0-5, dir: 1 = -, 0 = +

Jog Off(axis#) // axis# = 0-5, stops that axis from joging

RefCombination(int number)

1 = ref X  
2 = ref Y  
3 = ref X&Y same time,  
4 = ref Z  
5 = ref X&Z same time  
6 = ref Y&Z same time  
7 = ref X&Y&Z same time  
8 = ref A  
9 = ref X&A same time  
10 = ref Y&A same time  
11 = ref X&Y&A same time  
12 = ref Z&A same time  
13 = ref X&Z&A same time  
14 = ref Y&Z&A same time  
15 = ref X&Y&Z&A same time  
16 = ref B  
17 = ref X&B same time  
18 = ref Y&B same time  
19 = ref X&Y&B same time  
20 = ref Z&B same time  
21 = ref X&Z&B same time  
22 = ref Y&Z&B same time  
23 = ref X&Y&Z&B same time  
24 = ref A&B same time  
25 = ref X&A&B same time  
26 = ref Y&A&B same time  
27 = ref X&Y&A&B same time  
28 = ref Z&A&B same time  
29 = ref X&Z&A&B same time  
30 = ref Z&Y&A&B same time  
31 = ref X&Y&Z&A&B same time  
32 = ref C  
33 = ref X&C  
34 = ref Y&C  
35 = ref X&Y&C,  
36 = ref Z&C

```
37 = ref X&Z&C  
38 = ref Y&Z&C  
39 = ref X&Y&Z&C  
40 = ref A&C  
41 = ref X&A&C,  
42 = ref Y&A&C  
43 = ref X&Y&A&C  
44 = ref Z&A&C  
45 = ref X&Z&A&C  
46 = ref Y&Z&A&C,  
47 = ref X&Y&Z&A&C  
48 = ref B&C  
49 = ref X&B&C  
50 = ref Y&B&C  
51 = ref X&Y&B&C,  
52 = ref Z&B&C  
53 = ref X&Z&B&C  
54 = ref Y&Z&B&C  
55 = ref X&Y&Z&B&C  
56 = ref A&B&C,  
57 = ref X&A&B&C  
58 = ref Y&A&B&C  
59 = ref X&Y&A&B&C  
60 = ref Z&A&B&C  
61 = ref X&Z&A&B&C,  
62 = ref Y&Z&A&B&C  
63 = ref X&Y&Z&A&B&C
```

GetCoord("Question") //this opens a dialog box that your question appears, and you can enter coordinates for x, y, z and a. The next 4 functions will get the values you have entered.

GetXCoor() //see GetCoord above

GetYCoor() //see GetCoord above

GetZCoor() //see GetCoord above

GetACoor() //see GetCoord above

SwapAxix( 2,5) //axis are 0-7, x, y, z, a, b, c, s

ResetAxisSwap()

GetDROString(axis#) //axis# 0-6, returns the axis dro value as a "String"

SetFormula("math formula", axis#) //this will set a "Formula" into the "Axis formula" box.

3). Tool related:

GetToolChangeStart(double) //Axis 0-6, in machine coordinates

ToolLengthOffset() //gets the offset of the current tool

SetCurrentTool(Tool#) //sets DRO 824

4). Feed Related:

CommandedFeed() //get the current Feedrate

SetFeedRate(Rate) //sets the current Feedrate

5). Spindle Related:

GetRPM() //get the programmed Spindle speed

SetSpinSpeed(rpm) //set Spindle Speed commanded DRO

SetPulley(pulley#) //set the pulley number

6). File Related:

OpenDigFile() //Open a file last directory chosen

CloseDigFile() // opposite of above

OpenSubroutineFile("path\to\subrouting.tap")

7). Function Related:

THCOn() //turn on the THC output

THCOFF() //turn off the THC output

ZeroTHC() //zero the THC head

StartTHC() //start THC

EndTHC() //end THC

GetLEDCondition(Led) //Led as number, returns a bool

GetFloodCond() // bool is flood on

GetMistCond() //bool is mist on

GetSpindleCond() //bool is spindle on

SetTriggerMacro(macro#) //int macro #

SetIJAbs() //set to IJ Absolute coord. sys

SetIJInc() //set to IJ Incremental coord. sys

SetIJMode(mode) //mode 0-1, 0=IJ Abs, 1=IJ inc.

GetIJMode() //returns the IJ mode, see set IJ above.

IsEstop() //estop status, 1= in estop, 0 = running

IsSafeZ()

GetMessage() //Returns the OEM error message

SetModPlugString( "message" ,cfg# , Local address#)

RetractMode() //returns the Retract mode type.

IsProbing() // returns true if in a G31 routine

### 8). Threading Lathe Related:

tXStart()  
tZStart()  
tEndX()  
tEndZ()  
tClearX()  
tLead()  
tSpring()  
tFirstPass()  
tChamfer()  
tTaper()  
tInFeed()  
tDepthLastPass()  
InFeeds(iteration) // iteration? 😊  
ThreadDepth(iteration) // iteration? 😊  
tTapers(iteration) // iteration? 😊  
GetMinPass()

### 9). Port Related:

Writing:

Call SendFIFO("M104 S" & S\$ & Chr(10)& Chr(13))

Reading:

D\$ = GetFifoEntry()

ClearFiFo() //clears the serial FiFo buffer

SendFIFObyte(SHORT byte);

SendFIFOword(SHORT data);

### 10). Odds and Ends:

VB Timers //

There are 24 timers, numbered from timer 0 to timer 23.

SetTimer(x) , will reset that timer to 0.

N = GetTimer(x) , will tell you how much time has passed since it was set to zero. Granularity is in micro seconds.

Example:

```

if IsActive( INPUT1 ) then
if( Timer( 1 ) > 30 ) then
Speak" 30 seconds have elapsed"
SetTimer( 1 )
endif
else
SetTimer(1)
end if

```

Set Trigger Macro using “Push User Button” in Brians:

First, you dont put the code in a button, you put it in a macro file. For example file: m600.m1s  
SetMessage( "This is a macro call..")

Then , you have to set that macro to be the default macro call with a call to SetTriggerMacro( 600 ) at some point in the program, an init string could do that if the SetTriggerMacro call were in another macro file that is called on startup. Then the brain will execute m600 whenever that brain termination code is called.

To Write the Tool Table Data (and tool desc), out to a file to print:

```

textFilePath = "C:\mach3\ToolInfo.txt"
Set objFSO = CreateObject("Scripting.FileSystemObject")
Set objTextFile = objFSO.CreateTextFile(textFilePath)
Do Until num=225
num=num+1
N = GetToolDesc(num)
D = GetToolParam(num,1)
L = GetToolParam(num,2)
WD= Gettoolparam(num,3)
WL= Gettoolparam(num,4)
Dt= Date()
Tm= Time()
If N <>"Empty" Then
objTextFile.WriteLine("*Tool"& num &" * "& N &" *Diameter: "& D &
*Length: "& L &" *Wear Diam"&WD &" *WearLength"&WL & Chr(13) & Chr
(10))
Else
End If
Loop

objTextFile.WriteLine("**")
objTextFile.WriteLine(" Date: " &Dt &" Time: " &Tm)

objTextFile.Close
Dim sCOMMAND As String
sCOMMAND="print c:\mach3\toolinfo.txt"
Shell("c:\winnt2\system32\cmd.exe /c" & sCOMMAND)
End

```

Deg = Rad\* 57.29577

Multi-Start Threads:

Put in #99066 = start angle for the thread in the code  
so if you want to do 3 start thread then

```
#99066 = 0
threading code
#99066 = 120
same threading code
#99066 = 240
same threading code
```

66 is the DRO number of the start angle for a thread. When used with  
#99(DRO number) the DRO is accessible in Gcode.

#### Sending Keys

You can easily send keys to the active window, as if the user was pressing keys on the keyboard by using the SendKeys statement.

```
Shell "notepad", vbNormalFocus
```

```
SendKeys "This is a test string"
```

The code above runs notepad, and sends the keys 'This is a test string' to it. If you want to use special keys, such as ENTER or TAB, and keys that represent actions rather than characters, use the codes shown below:

#### Key Code

```
BACKSPACE {BACKSPACE}, {BS}, or {BKSP}
BREAK {BREAK}
CAPS LOCK {CAPSLOCK}
DEL or DELETE {DELETE} or {DEL}
DOWN ARROW {DOWN}
END {END}
ENTER {ENTER} or ~
ESC {ESC}
HELP {HELP}
HOME {HOME}
INS or INSERT {INSERT} or {INS}
LEFT ARROW {LEFT}
NUM LOCK {NUMLOCK}
PAGE DOWN {PGDN}
PAGE UP {PGUP}
PRINT SCREEN {PRTSC}
RIGHT ARROW {RIGHT}
SCROLL LOCK {SCROLLLOCK}
TAB {TAB}
UP ARROW {UP}
F1 {F1}
F2 {F2}
F3 {F3}
F4 {F4}
F5 {F5}
F6 {F6}
F7 {F7}
F8 {F8}
F9 {F9}
F10 {F10}
F11 {F11}
F12 {F12}
F13 {F13}
F14 {F14}
F15 {F15}
F16 {F16}
```

To specify keys combined with any combination of the SHIFT, CTRL, and ALT keys, precede

the key code with one or more of the following codes:

Key Code  
SHIFT +  
CTRL ^  
ALT %

To specify that any combination of SHIFT, CTRL, and ALT should be held down while several other keys are pressed, enclose the code for those keys in parentheses. For example, to specify to hold down SHIFT while E and C are pressed, use "+(EC)". To specify to hold down SHIFT while E is pressed, followed by C without SHIFT, use "+EC".

To specify repeating keys, use the form {key number}. You must put a space between key and number. For example, {LEFT 42} means press the LEFT ARROW key 42 times; {h 10} means press H 10 times.

Parametric Programming:

The macro code is shown in the ( ) after the macro call

Example code:

```
#3=3
o100
G0X#3
#3=[#3+1]
M9999 (If (GetVAR(3) > 6) Then Code" (END M9999)" Else
code"M98 P100 ")
m30
%
```

New Command:

(Comming out at some point after vs. 3.043.000)

CodeSingle("G & M Code here") //This command will be a combination of a Movement command coupled with a "While IsMoving()" built into it. Thus when you put a movement code into this, that code will complete before dropping out to the next VB code line.

'Enjoy Scott "Poppa Bear" Shafer